MEASUREMENTS AND MODELING OF TEMPERATURE-STRAIN RATE DEPENDENT UNIAXIAL AND PLANAR EXTENSIONAL VISCOSITIES FOR BRANCHED LDPE POLYMER MELT

Martin Zatloukal*

Polymer Centre, Faculty of Technology, Tomas Bata University in Zlin, Vavreckova 275, 762 72 Zlin, Czech Republic

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*Corresponding author: mzatloukal@ft.utb.cz

ABSTRACT

In this work, novel rectangle and circular orifice (zero-length) dies have been utilized for temperature-strain rate dependent planar and uniaxial extensional viscosity measurements for the LDPE polymer melt by using standard twin bore capillary rheometer and Cogswell model and the capability of five different constitutive equations (novel generalized Newtonian model, original Yao model, extended Yao model, modified White-Metzner model, modified Leonov model) to describe the measured experimental data has been tested. It has been shown that chain branching causes the strain hardening occurrence in both unixial and planar extensional viscosities and its maximum is shifted to the higher strain rates if the temperature is increased. The level of uniaxial extensional strain hardening for the branched LDPE sample has been found to be higher in comparison with the planar extensional viscosity within wide range of temperatures.

INTRODUCTION

The extensional viscosity represents key rheological parameter allowing understanding the molecular structure of the polymers as well as polymer processing at which the polymer melts are stretched [1-27]. Due to the fact that generation and control of the extensional flow is difficult, experimental determination of the extensional viscosity is a problem [28-32]. Probably the most challenging rheological task is experimental determination of planar extensional viscosity as one can see from very small numbers of experimental data available in the open literature [1-2, 12-16, 33]. With the aim to understand this important rheological parameter in more detail, in this work, novel rectangle and circular orifice dies [34-35] have been utilized for planar and uniaxial extensional viscosity measurements for branched LDPE by using standard twin bore capillary rheometer and Cogswell model [6, 12] and the capability of five different constitutive equations [36-42] to describe the measured experimental data has been tested.

EXPERIMENTAL

In this work, extrusion coating, branched LDPE CA820 from Borealis Polyolefine was used. Linear viscoelastic properties (storage modulus, loss modulus, and complex viscosity) were measured on Advanced Rheometric Expansion System ARES 2000 (Rheometrics Scientific, USA) in parallel plates geometry mode (plates diameter of 25 mm) within 0.1 s^{-1} up to 100 s^{-1} frequency range at 1% shear strain to guarantee linear viscoelasticity regime only. In order to get storage and loss moduli for a large range of frequencies, the measurements were performed in a wide range of temperatures (130–250°C). Possible degradation at high temperatures was suppressed

by inert nitrogen atmosphere. The well-known time-temperature-superposition principle was used to generate master curves for particular reference temperature. Twin-bore capillary rheometer Rosand RH7-2 (Rosand Precision, United Kingdom) was used for experimental determination of uniaxial and planar extensional viscosities by using long as well as orifice dies having the abrupt contraction (i.e. 180° entrance angle) and circular/rectangular shape (see Figures 1-2). The main advantage of both utilized orifice dies is the open downstream region design which eliminates any possibility for artificial pressure increase due to polymer melt touching the downstream wall [34-35]. Temperature measurement and control was performed at three separate zones in the barrel by using platinum resistance thermometers (PRTs) via microprocessor based board contained within the electronics rack communicating with the computer over a serial interface. Software running on the temperature board implements a three term (PID) control algorithm allowing independent variation of power for the three cuff barrel heaters with different heights and power ratings (1000W, 600W and 1000W).

The uniaxial and planar extensional viscosities have been determined through entrance pressure drop measurements by using the Cogswell model [6, 12] (see Table 1). In this table, $P_{0,U}$ and $P_{0,P}$ represents the entrance pressure drop measured on circular and rectangular orifice die, respectively, Q is the volume flow rate, R is the capillary die radius, w and h is the width and the gap size of the rectangle die, respectively, $P_{L,U}$ and $P_{L,P}$ represents the pressure drop through a long die having circular and rectangular shape, respectively, L is the length of the long die. It should be mentioned that the long die has L/(2R) = 16 (or L/h = 16) whereas the orifice die has L/(2R) = 0.1208 (or L/h = 0.1208) as suggested in [10].

The maximum attainable extensional strain during abrupt contraction flow in the capillary rheometer can be calculated as

$$\varepsilon_{\max} = \ln \left(\frac{A_b}{A_d} \right) \tag{1}$$

where A_b and A_d is the cross-sectional area of the barrel and the die, respectively [43]. The barrel diameter of the rheometer is 15mm, diameter of the circular die is 2mm and gap size of the rectangular die is 0.5mm. According to Eq. 1 ε_{max} is 4 and 3.6 for circular and rectangle orifice dies, respectively, and thus the average strain achievable in both die can be considered to be comparable. Importance of comparing the extensional viscosity at the same strain level is discussed in [43-45]. Note that high shear rate rheology was evaluated via 1mm diameter capillary dies.

THEORETICAL

Generalized Newtonian Fluid Model

In this work, recently proposed generalized Newtonian fluid model has been utilized [36-37]:

$$\tau = 2\eta \left(I_{|\mathsf{D}|}, II_{\mathsf{D}}, III_{\mathsf{D}} \right) D$$
⁽²⁾

where τ means the extra stress tensor, *D* represents the deformation rate tensor and η stands for the viscosity, which is not constant (as in the case of standard Newtonian law), but it is allowed to vary with the first invariant of the absolute value of

deformation rate tensor $I_{|D|} = tr(|D|)$, (where |D| is defined as $\sqrt{D \cdot D}$) as well as on the second $II_D = 2tr(D^2)$, and third, $III_D = det(D)$, invariants of D according to Eq. 3

$$\eta \left(I_{|\mathsf{D}|}, II_{\mathsf{D}}, III_{\mathsf{D}} \right) = A^{1 - f \left(I_{|\mathsf{D}|}, II_{\mathsf{D}}, III_{\mathsf{D}} \right)} \eta \left(II_{\mathsf{D}} \right)^{f \left(I_{|\mathsf{D}|}, II_{\mathsf{D}}, III_{\mathsf{D}} \right)}$$
(3)

where $\eta(II_D)$ is given by the well known Carreau-Yasuda model (with infinite viscosity η_{∞} equal 0), Eq. 4 and $f(I_{|D|}, II_D, III_D)$ is given by Eq. 5

$$\eta(II_{\rm D}) = \frac{\eta_0 a_{\rm T}}{\left[1 + \left(\lambda a_{\rm T} \sqrt{II_{\rm D}}\right)^a\right]^{\left(\frac{1-n}{a}\right)}}$$
(4)

$$f(I_{|\mathsf{D}|}, II_{\mathsf{D}}, III_{\mathsf{D}}) = \left\{ tanh\left[\alpha a_{\mathsf{T}} \left(1 + \frac{1}{4(\sqrt{3})^3} \right)^{-\psi} \left(\left| 1 + \frac{III_{\mathsf{D}}}{II_{\mathsf{D}}^{3/2}} \right| \right)^{\psi} \frac{\sqrt[3]{4|III_{\mathsf{D}}|} + I_{|\mathsf{D}|}}{3} + \beta \right] \frac{1}{tanh(\beta)} \right\}^{\zeta}$$
(5)

here A, η_0 , λ , a, n, α , ψ , β , ζ are 9 adjustable parameters and a_T is temperature shift factor defined by the Arrhenius equation:

$$a_{\rm T} = exp\left[\frac{E_{\rm a}}{R}\left(\frac{1}{273.15+T} - \frac{1}{273.15+T_{\rm r}}\right)\right]$$
(5)

where E_a is the activation energy, *R* is the universal gas constant, T_r is the reference temperature and *T* is local temperature.

The model utilizes 4 parameters (η_0 , λ , a, n) identifiable from shear viscosity, 4 parameters (A, α , β , ζ) identifiable from uniaxial extensional viscosity and 1 parameter (ψ), which can be determined from planar extensional viscosity. The key feature of this model is utilization of the new tensor called absolute value of deformation rate tensor, |D|, which characterizes deformation rate intensity in a particular direction (similarly to D) but without the information about its orientation

(positive or negative). Its first invariant $I_{|D|}$ becomes nonzero in extensional flows and thus the model has capability to predict uniaxial as well as planar extensional viscosities [36].

Original Yao Model

Original Yao model is a non-Newtonian fluid model with an objective vorticity tensor utilizing two different time scales for strain relaxation and rotation recovery [38]. Mathematically it takes the following form:

$$\tau = GB^* + 2\eta_S D_S \tag{6}$$

where G is a modulus related to the chain structure, B^* is an elastic strain tensor describing the conformation of the molecular coil

$$B^* = \left[\exp\left(n_0 \lambda a_T \overline{L}^*\right) \cdot \exp\left(n_0 \lambda a_T \overline{L}^*^T\right) \right]^{\frac{1}{n_0}}$$
(7)

 η_S is the slip viscosity defined as

$$\eta_{S} = \frac{\mu_{S} a_{T}}{\left[1 + \left(K_{1} a_{T} \sqrt{II_{D_{S}}}\right)^{2}\right]^{(1-k)/2}}$$
(8)

where II_{D_S} is second invariant of deformation rate tensor for chain slip, D_S , defined as follows

$$D_{S} = \frac{1}{2} \left[\left(L - \overline{L^{*}} \right)_{\perp} + \left(L - \overline{L^{*}} \right)_{\perp}^{T} \right]$$
(9)

Here, *L* is the velocity gradient, $\overline{L^*}$ is the adjusted objective velocity gradient introduced by Yao in [38] to enforce that the calculated stretch of the polymer coil does not exceed the ceiling stretch S₀. The symbol $_{\perp}$ represents projection onto the

principal directions of B^* . Even if the model utilizes 7 adjustable parameters (η_0 , λ , S_0 , μ_S/η_0 , n_0 , K_1 , k where $G=\eta_0/\lambda$), its number is reduced to 6 for description of extensional flows because the parameter n_0 disappears in such a cases. Thus, all 6 original Yao model parameters (η_0 , λ , S_0 , μ_S/η_0 , K_1 , k) were identified on the uniaxial extensional viscosity only.

Extended Yao Model

Extended Yao model is a recently proposed non-Newtonian fluid model with finite stretch and rotational recovery utilizing specific finite chain dynamics to treat the combined effects of finite stretch and disentanglement [39], which reduce total number of model parameters from seven to five in comparison with the original Yao model. The extended Yao model is given by the following equations

$$\tau = \frac{\eta_0}{\lambda \left[1 - \frac{S}{S_0}\right]^{\beta_0}} B, \qquad (10)$$

$$B = \left\{ \exp\left[n_0 \lambda a_T \left(1 - \frac{S}{S_0}\right)L\right] \cdot \exp\left[n_0 \lambda a_T \left(1 - \frac{S}{S_0}\right)L^T\right] \right\}^{\frac{1}{n_0}},$$
(11)

where *B* is the generalized Finger tensor representing the elastic strain accumulated in the polymer coil and *S* is an equivalent stretch, defined as $S = \sqrt{\frac{1}{6} \ln B : \ln B}$. The model utilizes 5 adjustable parameters (η_0 , λ , S_0 , n_0 , β_0), but its number is reduced to 4 for description of extensional flows due to disappearance of the parameter n_0 (i.e. similarly as in the case of original Yao model). Hence, all 4 extended Yao model parameters (η_0 , λ , S_0 , β_0) were identified on the uniaxial extensional viscosity only. It is important to mention that according to Yao [39], the β_0 is the strain hardening parameter ($0 \le \beta_0 \le 1$) and S_0 is the celling stretch for disentanglement (typically in the range of 1 to 3).

Modified White–Metzner Model

Modified White-Metzner model constitutive equation is a simple Maxwell model for which the viscosity and relaxation time are allowed to vary with the second invariant of the strain rate deformation tensor [40]. It takes the following form:

$$\tau + \lambda (II_{\rm D})^{\nabla} = 2\eta (II_{\rm D})D \tag{12}$$

where τ is the upper convected time derivative of stress tensor, *D* is the deformation rate tensor, *H*_D is the second invariant of the rate of deformation tensor, $\lambda(H_D)$ stands for the deformation rate-dependent relaxation time and $\eta(H_D)$ is the deformation ratedependent viscosity. Although this modification improves the behaviour in steady shear flows, in extensional flows the model predicts unrealistic infinite extensional viscosity. This problem was overcome by Barnes and Roberts [40], who showed that, for specific functions of $\lambda(H_D)$ and $\eta(H_D)$ with (λ_0/K_2) < ($\sqrt{3}/2$) (see Eqs. (4) and (13)), the model does not predict infinite extensional viscosity and can be used for a very good description of extensional viscosity of a wide range of real polymer melts:

$$\lambda(II_{\rm D}) = \frac{\lambda_0 a_{\rm T}}{1 + K_2 a_{\rm T} II_{\rm D}} \tag{13}$$

where λ_0 and K_2 are constants. Eqs. (4, 12-13) together with the physical constraint for λ_0 and K_2 mentioned above represent the modified White–Metzner model. The model

utilizes 4 parameters (η_0 , λ , a, n) identifiable from shear viscosity and 2 parameters (λ_0 , K_2) identifiable from uniaxial extensional viscosity.

Modified Leonov Model

This constitutive equation is based on heuristic thermodynamic arguments resulting from the theory of rubber elasticity [41, 46-47]. Mathematically it is relating the stress and elastic strain stored in the material as:

$$\tau = 2 \left(c \frac{\partial W}{\partial I_1} - c^{-1} \frac{\partial W}{\partial I_2} \right)$$
(14)

where τ is the stress, and W, the elastic potential, depends on the invariants I_1 and I_2 of the recoverable Finger tensor c,

$$W = \frac{3G}{2(n_1+1)} \left\{ \left(1 - \phi\right) \left[\left(\frac{I_1}{3}\right)^{n_1+1} - 1 \right] + \phi \left[\left(\frac{I_2}{3}\right)^{n_1+1} - 1 \right] \right\}$$
(15)

where *G* denotes linear Hookean elastic modulus, ϕ and n_1 are numerical parameters. Leonov assumed that dissipative process act to produce irreversible rate of strain e_p

$$e_{p} = b \left[c - \left(\frac{I_{1}}{3} \right) \delta \right] - b \left[c^{-1} - \left(\frac{I_{2}}{3} \right) \delta \right]$$
(16)

which spontaneously reduces the rate of elastic strain accumulation. Here, δ is the unit tensor and *b* stands for dissipation function defined by Eq. (18). This elastic strain *c* is related to the deformation rate tensor *D* as follows

$$\overset{0}{c} - c \cdot D - D \cdot c + 2c \cdot e_p = 0 \tag{17}$$

where c is the Jaumann (corotational) time derivative of the recoverable Finger strain tensor. In this work, the neo-Hookean potential (i.e. $\phi = n_1 = 0$ in Eq. 15) and the dissipation function *b* proposed in [42] (see Eq. 18), have been employed.

$$b(I_1) = \frac{1}{4\lambda a_T} \left\{ \exp\left(-\xi \sqrt{I_1 - 3}\right) + \frac{\sinh\left[\nu(I_1 - 3)\right]}{\nu(I_1 - 3) + 1} \right\}$$
(18)

Here, ξ and v are adjustable parameters which are allowed to vary with relaxation time, λ . Thus, the model utilizes relaxation spectrum (in terms of finite number of λ_i and G_i pairs for given modes) identifiable from loss and storage moduli and 2 parameters (ξ , v) identifiable from uniaxial extensional viscosity.

RESULTS AND DISCUSSION

The generalized Maxwell model was employed to fit the measured frequency dependent loss and storage moduli for the tested LDPE material to generate discrete relaxation spectrum. Figure 3 shows that this model properly fits the measured data, which supports the reliability of the estimated relaxation spectrum. The Newtonian viscosity at 170°C (calculated from the relaxation spectrum) and the flow activation energy (determined via Arrhenius plot depicted in Figure 4) was found to be 4376.6 Pa.s and 52.251 kJ/mol, respectively.

The measured temperature-strain rate dependent uniaxial and planar extensional viscosities, together with the shear viscosity and model fits/predictions (model parameters are summarized in Tables 2-6), for the tested branched LDPE sample are provided in Figures 5-10.

First, the level of the strain hardening in uniaxial extensional viscosity is higher than in the planar extensional viscosity for the tested LDPE sample at all three temperatures (see Figures 5-6) which is in good agreement with the recent experimental work performed by D. Auhl et. al [33] on the cross-slot extensional rheometer. Experimental observation that the strain hardening is lower in planar extension than in uniaxial extension can be explained via differences in extensional flow kinematics and alignment strength (defined by Larson [48] as the strain invariants difference, I₁-I₂). In the uniaxial extension, material element is stretched in one direction and shrinks in another two directions, which leads to strong alignments of macromolecular chains along a single axis (I₁-I₂>0). However, in the planar extension, the chain alignment is neutral $(I_1-I_2=0)$ because the material is stretched in one direction, shrinks in another direction but remains constant in the third direction [48]. This means that during uniaxial extension of polymer melts, alignment of macromolecular chains (i.e. the stress level) is much higher than in the case of planar extension. Thus, the observed higher extensional strain hardening of LDPE melt in uniaxial extension having 3D character can be attributed to more aligned and 'constrained' chains in comparison with planar extension having only 2D nature. Moreover, the investigated LDPE melt is highly branched, i.e. when the stretched chains become sufficiently close to each other, new entanglements start to occur due the presence of chain branches, which increases the resistance against the extensional flow. Thus, entanglement network can be much more strengthened via presence of chain branches in the uniaxial extension due to 3D character of geometric condensation, in which chains moves close to each other more effectively, than in the

case of 2D planar extension. This may explain the observed extensional flow behaviour for the investigated LDPE melt.

Second, the maximum in both viscosities is shifted to the higher strain rates for increased temperature. It has been revealed recently [49-54] that the ratio of planar to uniaxial extensional viscosity, $\eta_{E,P}/\eta_{E,U}$, (i.e. the difference between the strain-hardening nature in planar and uniaxial elongation) controls the level of the unwanted neck-in phenomena (film width reduction occurring during the film casting process between the flat die and the chill/nip rolls) due to the fact that the middle of the film undergoes planar elongation whereas the material at the edge undergoes uniaxial elongation. Based on the film casting process modeling, the following relationship between neck-in, *NI*, and planar to uniaxial extensional viscosity ratio has recently been found [53]:

$$NI = \frac{1}{2} \left(W_{\rm D} - W_{\rm F} \right) \cong L \left\langle \frac{\eta_{\rm E,P}}{\eta_{\rm E,U}} \right\rangle_{L}^{1/2}$$
(19)

where W_D represents the die exit width, W_F the final film width, respectively, L is distance between the flat die and the chill/nip rolls and $\langle \eta_{E,P}/\eta_{E,U} \rangle$ is averaged planar to uniaxial extensional viscosity ratio. This suggests that the experimental evaluation of planar and uniaxial extensional viscosities can be considered as useful tool for optimization of the molecular structure of polymers utilized in the film casting technology to minimize neck-in phenomenon.

Third, the generalized Newtonian and both Yao models have higher capability to describe temperature-strain rate dependent uniaxial and planar extensional viscosities for both tested samples in comparison with modified White-Metzner models as visible

in Figures 8-10. This can be explained by the presence of additional parameter ψ in the generalized Newtonian model allowing to fit the deformation rate dependent planar extensional viscosity, which is not the case of the modified White-Metzner model. Even if the original Yao model shows a small tendency to over predict strain hardening in the measured planar extensional viscosity (see Figure 9), its overall capability to describe extensional rheology by using six physic-based material constants is very good due to implementation of finite stretch, disentanglement and slippage of polymer chains in this model. Surprisingly, the recently proposed four parameter extended Yao model shows even better capability to describe the measured extensional viscosity data than original six parameter Yao model due to its higher ability to predict planar extensional viscosity data as visible in Figure 9. This suggests that the extended Yao model is superior to the original Yao model. Interestingly, the modified Leonov model predictions, based on linear relaxation spectrum and nonlinear parameters ξ , v identified on the strain-rate dependent uniaxial extensional viscosity only, are in very good agreement with the measured strain-rate dependent planar extensional viscosity, both measured at comparable strains (see Figure 10). This supports the physics behind the modified Leonov model as well as reliability and applicability of the performed measurements. It is important to mention that number of parameters utilized in the modified Leonov model is much higher in comparison to other tested models. It utilizes 12 modes discrete linear relaxation spectrum and additional 12 pairs of corresponding non-linear parameters ξ , v identified from uniaxial extensional viscosity only (see Table 6). This makes the identification process for modified Leonov model much more complicated in comparison with low parametric models utilized in this work.

At the end of this chapter, main limitations of the Cogswell method, possible experimental difficulties and suggestions how to overcome them are provided and discussed.

- In the Cogswell method, inertia, shear normal stresses, Weissenberg-Rabinowitsch correction, slip, and fluid compressibility are neglected [1, 6, 17]. Thus the experimental set-up for the given polymer melt should be optimized to fulfil as much as possible the applied assumptions, where it is possible. For example, running experiments at higher temperatures should be preferred to minimize effect of shear elasticity, slip and melt compressibility.
- Orifice dies having virtually zero length rather than extrapolation Bagley plot method should be preferred in order to minimize errors in the entrance pressure drop measurements due to slip, viscous heating and compressibility effects.
- Even if the Cogswell method was found to be fairly accurate at high rates [11, 13, 45], it fails at low rates because the Trouton relationship is not handled correctly due to assumed kinematics [10, 55]. This problem can be overcome by using a specific orifice die having L/D ratio equal to 0.1208 as shown in [10].
- Improper orifice die design leads to unwanted wetting and accumulation of the polymer melt at the die exit region, which generates significant error in the

form of additional pressure drop [9, 11, 35, 56-58]. This problem can be avoided by using orifice dies with highly opened downstream region [9, 11, 34-35] (see Figures 1-2).

- The flow is no homogeneous at the entry region of the die because mixed shear and extensional flow occur at the same time. In order to enhance the extensional flow components, abrupt 180° entry angle dies can be used.
- Generated average values of extensional strain might be lower than those needed to reach steady state conditions. This can be overcome by increasing the barrel diameter and/or decreasing die diameter/gap size.

CONCLUSION

In this work, planar and uniaxial extensional viscosities for branched LDPE polymer melt has been determined through entrance pressure drop technique on conventional twin bore capillary rheometer by using novel circular and rectangle orifice dies and the obtained experimental data has been described by four different constitutive equations. It has been showed that chain branching causes the strain hardening occurrence in both, uniaxial and planar extensional viscosities and its maximum is shifted to the higher strain rates if the temperature is increased. The level of uniaxial extensional strain hardening for the branched LDPE sample has been found to be higher in comparison with the planar extensional viscosity within wide range of temperatures. It has been found that recently proposed non-Newtonian fluid model [36-37] and especially a few parametric extended Yao model [39] can represent steady shear, uniaxial and planar extensional viscosities for branched LDPE reasonably well. On the other hand, the modified White-Metzner model has failed in the prediction of

the planar extensional viscosity. It has been revealed that the capability of the original Yao model to describe both measured extensional viscosities via few physics-based material parameters is good with small tendency to over predict strain hardening in the planar extensional viscosity. Moreover, it has been concluded that the extended Yao model is superior to original Yao model due to its higher overall capability to fit/predict measured extensional viscosity data by lower number of material parameters. Interestingly, the modified Leonov model predictions for the planar extensional viscosities have been revealed to be in very good agreement with the experimental data, which supports physics behind the model and reliability of the performed measurements.

It is believed that the proposed novel orifice die design for the planar extensional viscosity measurements can be considered as a very useful tool for better understanding of the polymer melt molecular structure, processing instabilities, optimization of polymer blends composition as well as for the constitutive equation testing purposes.

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	Uniaxial extensional flow	Planar extensional flow
Apparent shear rate	$\dot{\gamma}_{\mathrm{app,U}} = rac{4Q}{\pi R^3}$	$\dot{\gamma}_{\rm app,P} = rac{6Q}{wh^2}$
Corrected shear stress	$\tau_{\rm xy, corr, U} = \frac{\left(P_{\rm L, U} - P_{0, U}\right)R}{2L_{\rm U}}$	$\tau_{\rm xy, corr, P} = \frac{\left(P_{\rm L, P} - P_{\rm 0, P}\right)h}{2L_{\rm P}}$
Apparent index of non- Newtonian behaviour	$n_{\rm U} = \frac{d \log(\tau_{\rm xy, corr, U})}{d \log(\dot{\gamma}_{\rm app, U})}$	$n_{\rm P} = \frac{d \log(\tau_{\rm xy, corr, P})}{d \log(\dot{\gamma}_{\rm app, P})}$
Extensional stress	$\sigma_{\rm E,U} = \frac{3}{8} (n_{\rm U} + 1) P_{0,\rm U}$	$\sigma_{\rm E,P} = \frac{1}{2} (n_{\rm P} + 1) P_{0,\rm P}$
Extensional strain rate	$\dot{\varepsilon}_{\rm U} = \frac{4\tau_{\rm xy, corr, U} \dot{\gamma}_{\rm app, U}}{3(n+1)P_{0, \rm U}}$	$\dot{\varepsilon}_{\rm U} = \frac{2\tau_{\rm xy, corr, P} \dot{\gamma}_{\rm app, P}}{3(n+1)P_{0, P}}$
Extensional viscosity	$\eta_{\mathrm{E,U}} = rac{\sigma_{\mathrm{E,U}}}{\dot{arepsilon}_{\mathrm{U}}}$	$\eta_{\mathrm{E,P}} = \frac{\sigma_{\mathrm{E,P}}}{\dot{\varepsilon}_{\mathrm{P}}}$

Table 1. Cogswell model summarization for uniaxial/planar extensional viscosity determination [6, 12].

TABLE 2. Generalized Newtonian model parameters for $T = 170^{\circ}$ C

η_0	λ	а	n	A	β	ζ	A_1	ψ
(Pa·s)	(s)	(-)	(-)	(s)	(-)	(-)	(P a)	(-)
4376.6	0.2151	0.4919	0.3464	0.051671	0.0675	0.056076	2.4.10-5	8

TABL	E 3. Origi	nal Yao moo	lel paramete	rs for $T = 1^{\circ}$	70°C
ηο	λ	So	μs/η0	K_1	k
(Pa.s)	(s)	(-)	(-)	(s)	(-)
4376.6	0.08	1.54975	10.94593	3.15680	0.48774

TABL	E 4. Extend	ed Yao moo	del paramet	ers for $T =$	170°C
	η_0	λ	So	βo	
	(Pa.s)	(s)	(-)	(-)	
	4376.6	0.3965	2.50607	0.08487	

TABLE 5.	Modified	White-M	etzner model	parameters f	for $T =$	170°C
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I ADLE S	. Wioum	cu winte-r	Metzner mo	del parameters	3 101 T = 170 C
η_0	λ	а	n	λο	K_2
(Pa [·] s)	(s)	(-)	(-)	(s)	(s)
4376.6	0.2151	0.4919	0.3464	0.936	1.1286

	Maxwel	l parameters	mLeonov model		
i	$\lambda_{i}(s)$	G _i (Pa)	ξ	v	
1	0.00070958	83406.20000	0	1.000	
2	0.00221000	40900.00000	0	1.000	
3	0.00687000	14940.90000	2.000	0.025	
4	0.02137000	12444.40000	1.180	0.020	
5	0.06647000	5911.720000	0.750	0.020	
6	0.20680000	2964.370000	0.500	0.020	
7	0.64336000	1233.070000	0.100	0.020	
8	2.00152000	458.1260000	0.090	0.080	
9	6.22686000	95.86140000	0	1.000	
10	19.3721000	14.70970000	0	1.000	
11	60.2679000	4.097244707	0	1.000	
12	187.497000	0.071474080	0	1.000	

TABLE 6. Modified Leonov model parameters for $T = 170^{\circ}$ C



FIGURE 1. Patented circular orifice die with abrupt entry utilized for uniaxial extensional viscosity measurements developed in [11, 34].



FIGURE 2. Patented rectangle dies for planar extensional viscosity measurements [35]. **2a**) Sketch of the rectangle orifice die with abrupt entry. **2b**) Set of rectangle dies for the planar extensional viscosity measurements on twin bore capilary rheometer (left – long die, right – novel orifice die).



FIGURE 3. Comparison of Maxwell model with measured complex viscosity, storage and loss moduli for LDPE polymer in oscillatory shear flow at the reference temperature 170°C.



FIGURE 4. Arrhenius plot for LDPE sample.



FIGURE 5. Experimentally determined steady shear and uniaxial extensional viscosities for LDPE sample at three different temperatures (top – uniaxial extensional viscosity, bottom – shear viscosity).



FIGURE 6. Experimentally determined steady shear and planar extensional viscosities for LDPE sample at three different temperatures (top – planar extensional viscosity, bottom – shear viscosity).



FIGURE 7. Comparison between the utilized generalized Newtonian/modified White-Metzner model fits (solid lines) and measured steady shear viscosities (symbols) for LDPE sample.



FIGURE 8. Comparison between the utilized Generalized Newtonian model fits/predictions (solid lines) and measured uniaxial and planar extensional viscosities (symbols) for LDPE sample at three different temperatures.



FIGURE 9. Comparison between the utilized model fits/predictions (solid lines) and measured uniaxial and planar extensional viscosities (symbols) for LDPE sample at three different temperatures (top – Original Yao model, bottom – Extended Yao model).



FIGURE 10. Comparison between the utilized model fits/predictions (solid lines) and measured uniaxial and planar extensional viscosities (symbols) for LDPE sample at three different temperatures (top – Modified White-Metzner model, bottom – Modified Leonov model model).